




電磁気観測による火山活動監視

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- 1) ACTIVEシステムによる火山活動監視
 - 2) 無人ヘリによる繰り返し空中磁気測量

EM observations

(pre-)Maxwell equations

Ampere's law $\nabla \times H = \sigma E + J$

Faraday's law $\nabla \times E = -\frac{\partial}{\partial t} \mu_0 (H + M)$
 $\equiv -\frac{\partial}{\partial t} (\mu H)$

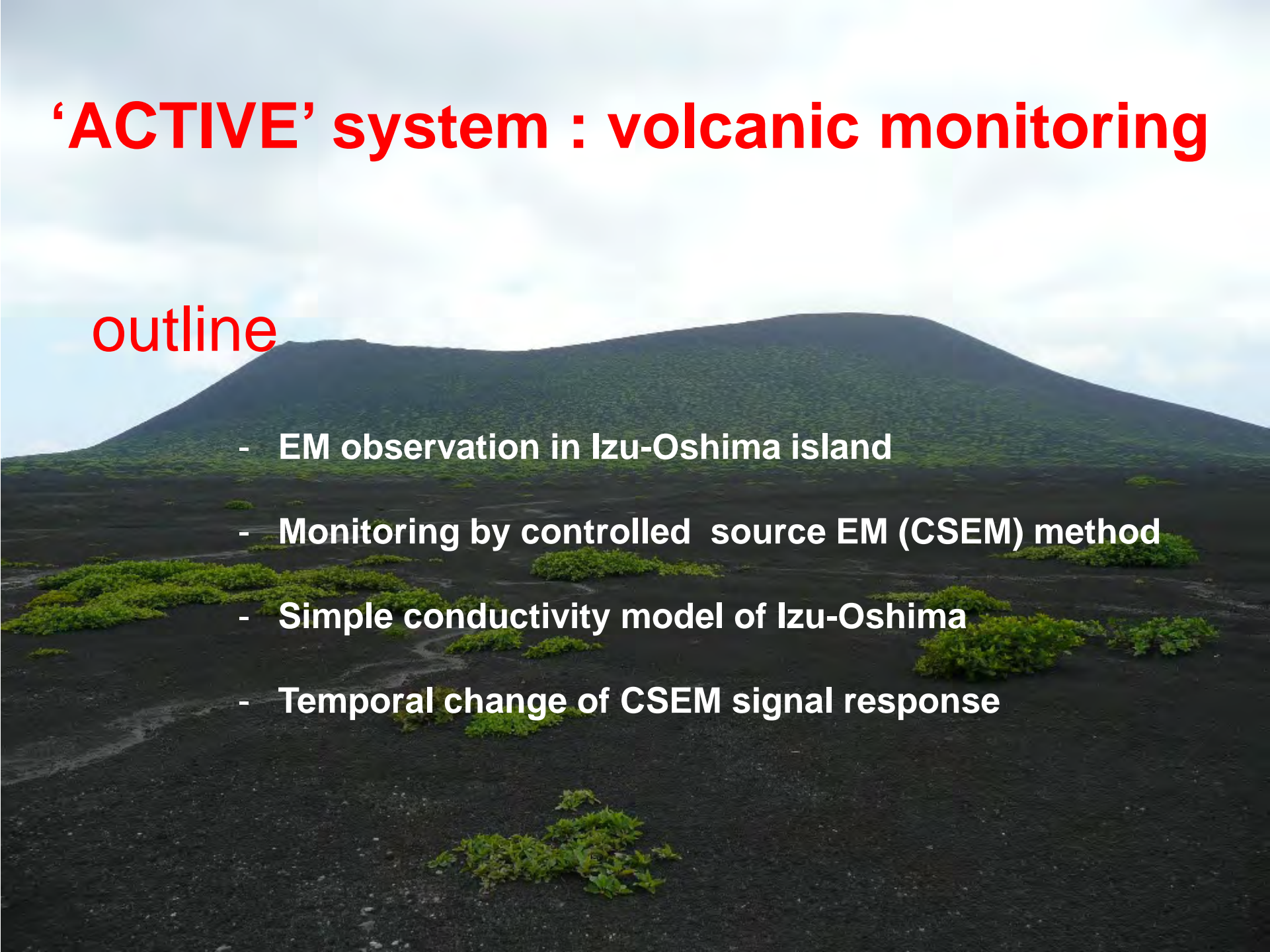
Observables: electric field E , magnetic field H

- Target to monitor:
- electrical conductivity σ
 - (physical property):
 - magnetization M or magnetic permeability μ
 - (non-Ohmic electric current density J)

'ACTIVE' system : volcanic monitoring

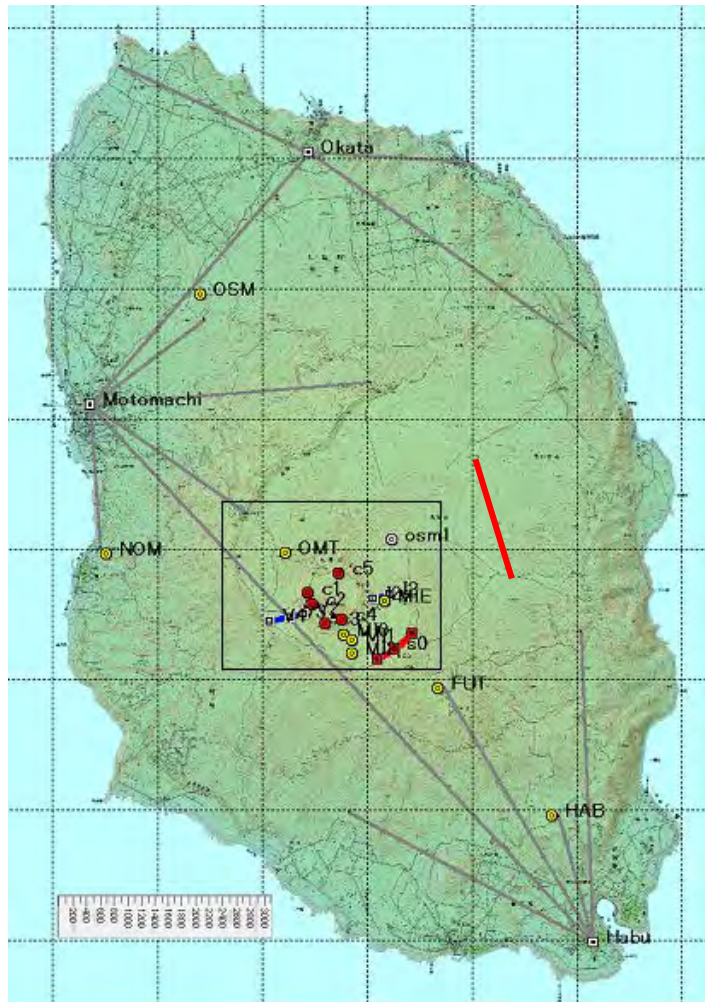
outline

- EM observation in Izu-Oshima island
- Monitoring by controlled source EM (CSEM) method
- Simple conductivity model of Izu-Oshima
- Temporal change of CSEM signal response

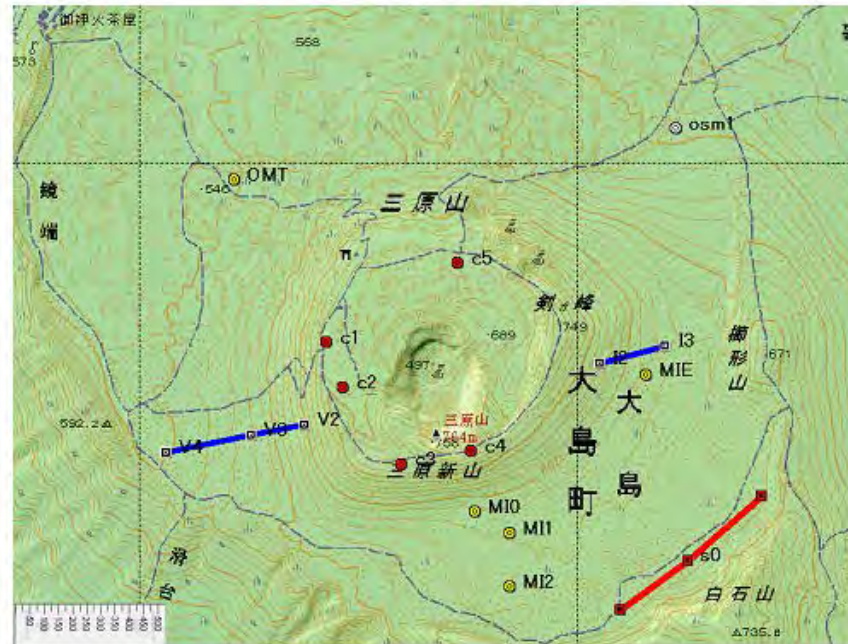


EM observation in Izu-Oshima

Data are transferred by wireless LAN.



- Proton
- ACTIVE receiver
- Fluxgate
- DC resistivity
- ACTIVE transmitter
- Network MT



Geomagnetic total intensity measurement 1968~

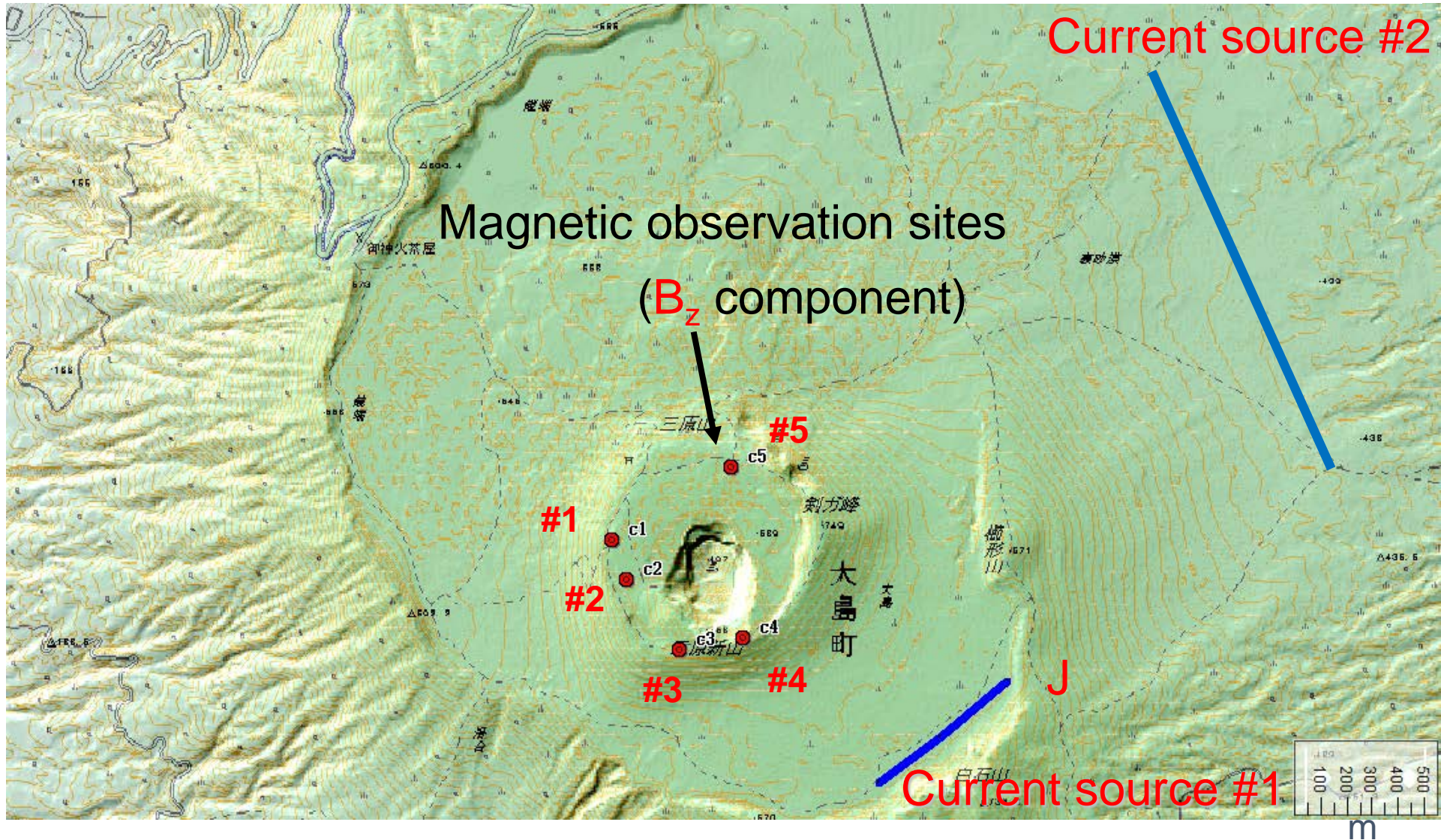
DC resistivity measurement 1975~

ACTIVE resistivity measurement (CSEM) 2003~



“ACTIVE” – CSEM system

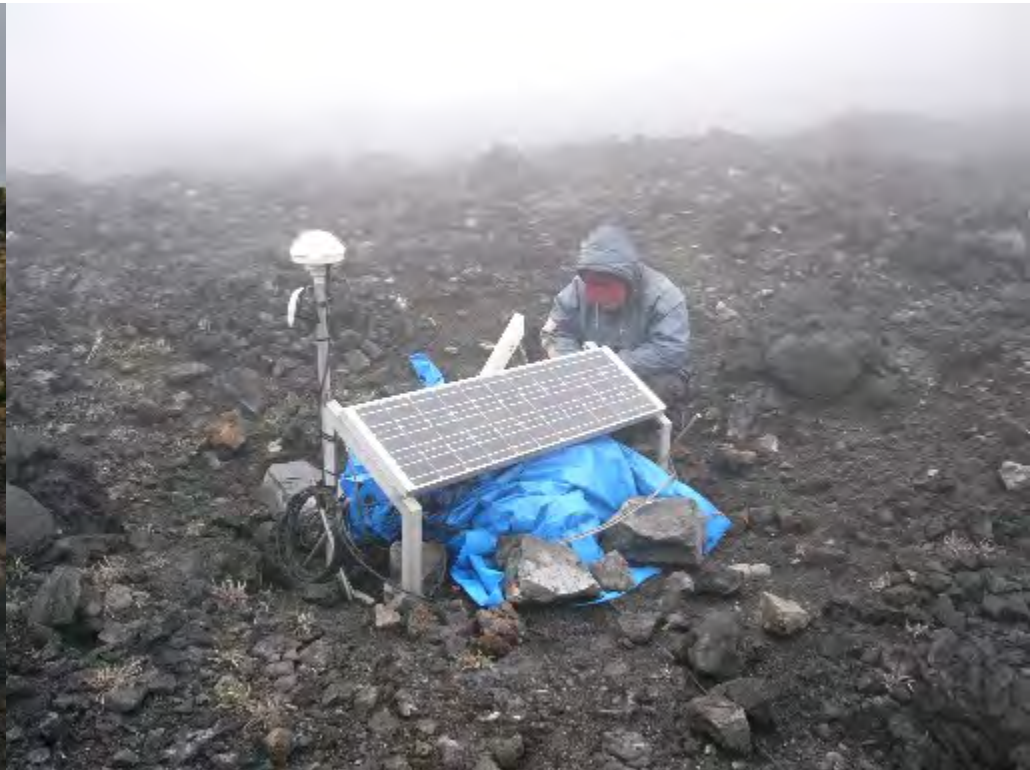
Array of **C**ontrolled **T**ransient electromagnetics for **I**maging **V**olcano **E**difice.
(Takahashi, 2006; Utada et al., 2007)



EM monitoring system of temporal change of conductivity structure by using the controlled electric current source

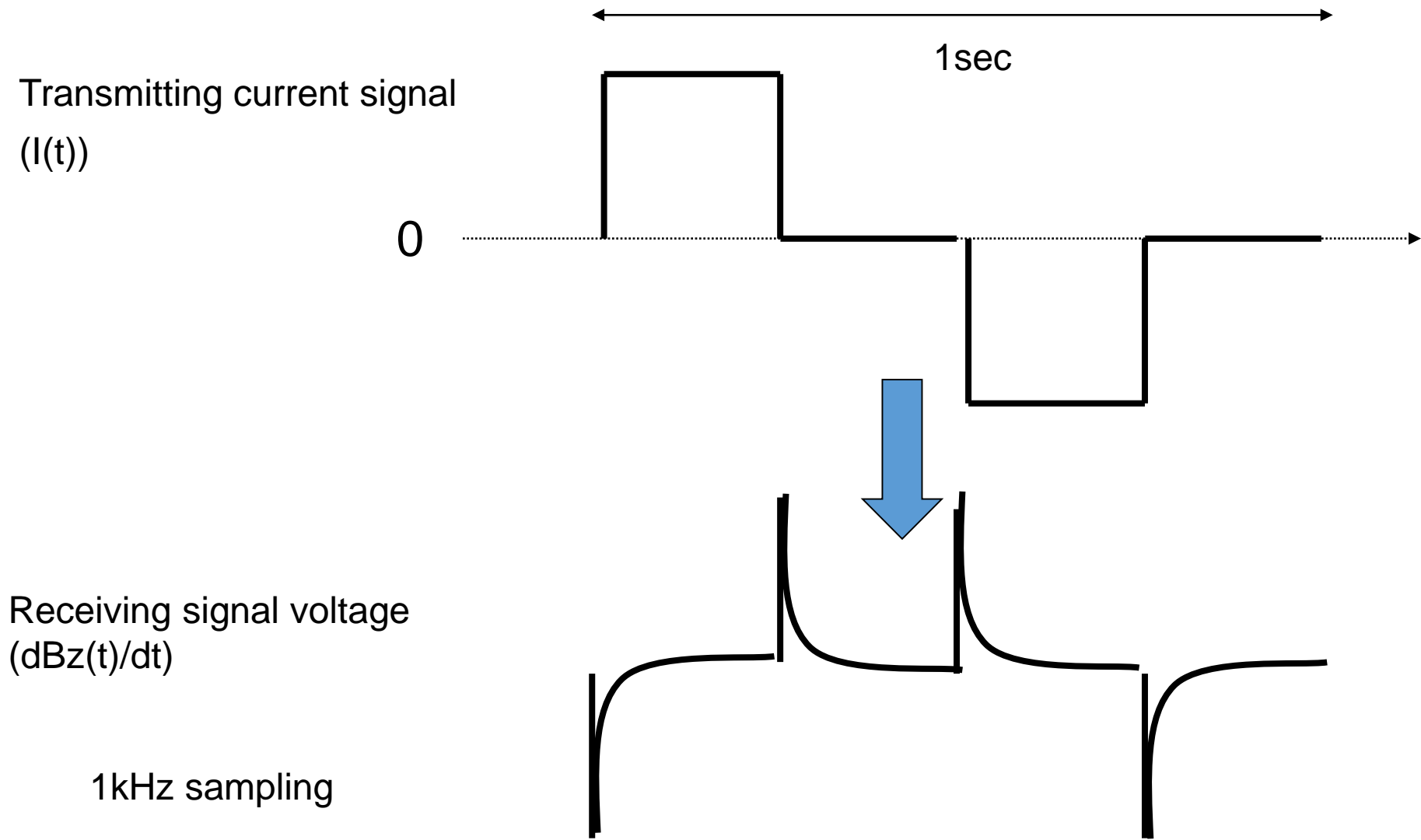


Transmitter of electric current source #1



Receiver system of magnetic signal

Schematic image of signal and received data

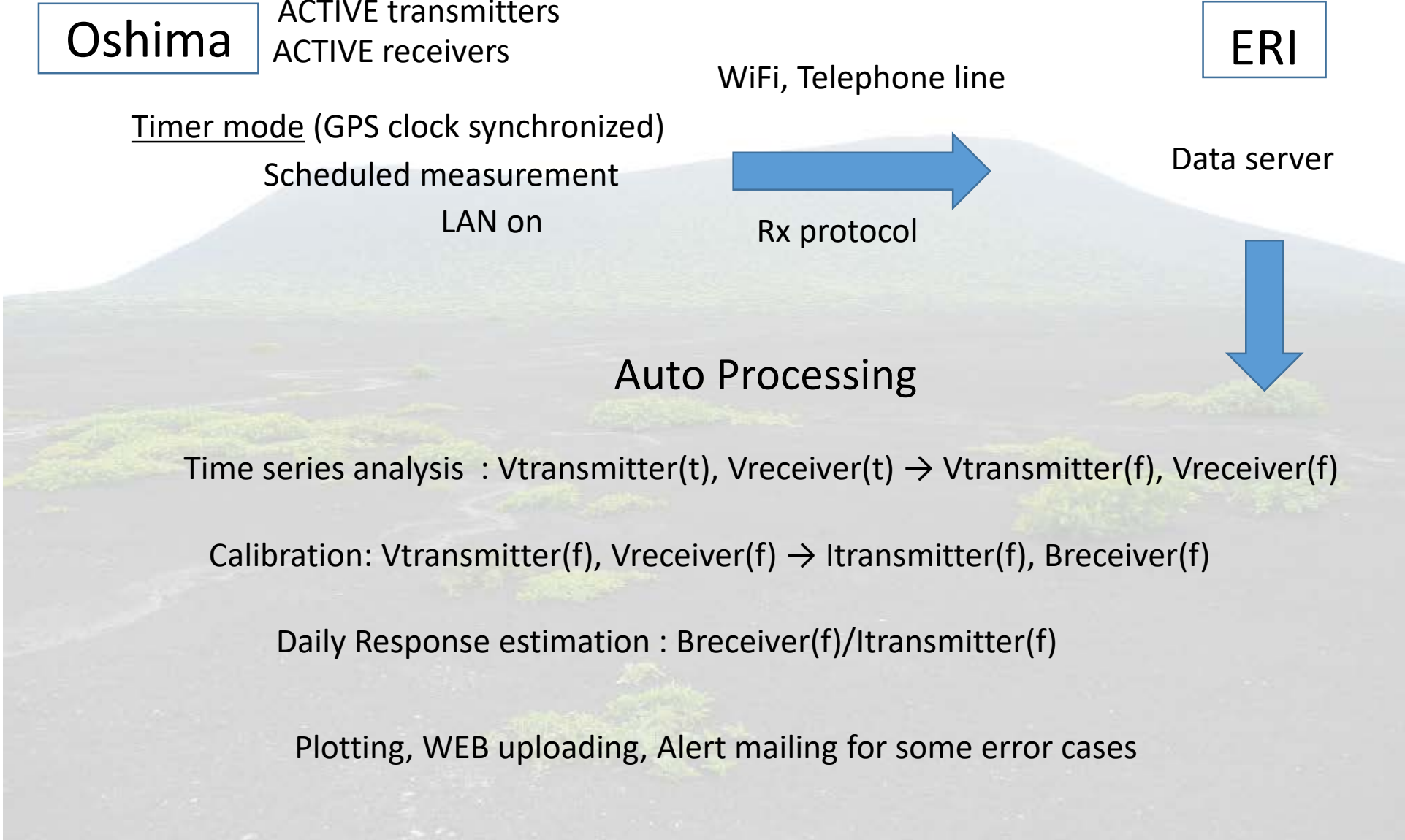


This measurement is done every mid-night.



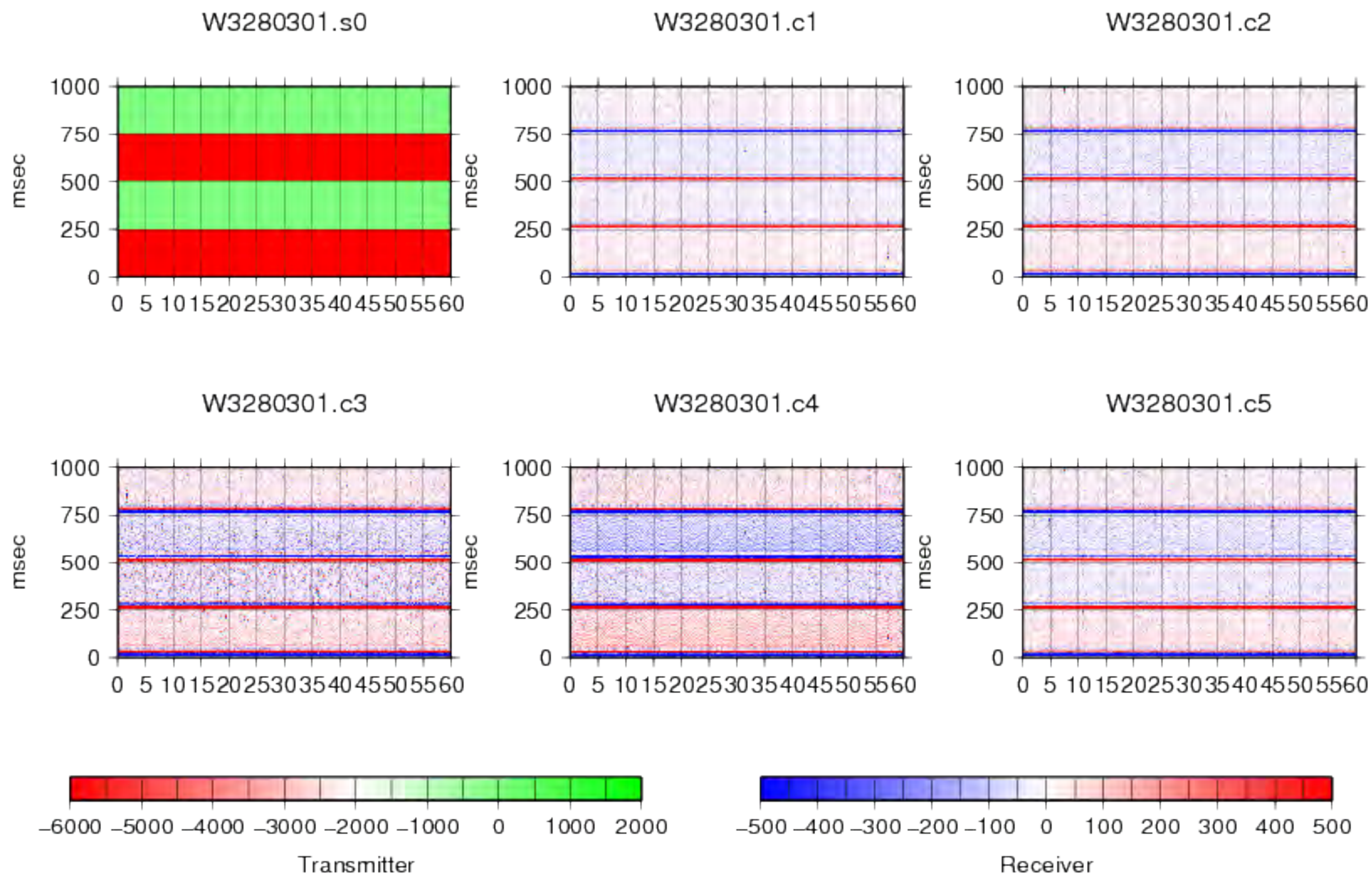
Estimate : $\text{Response}(f) = Bz(f) / I(f)$

Daily Data Auto Processing



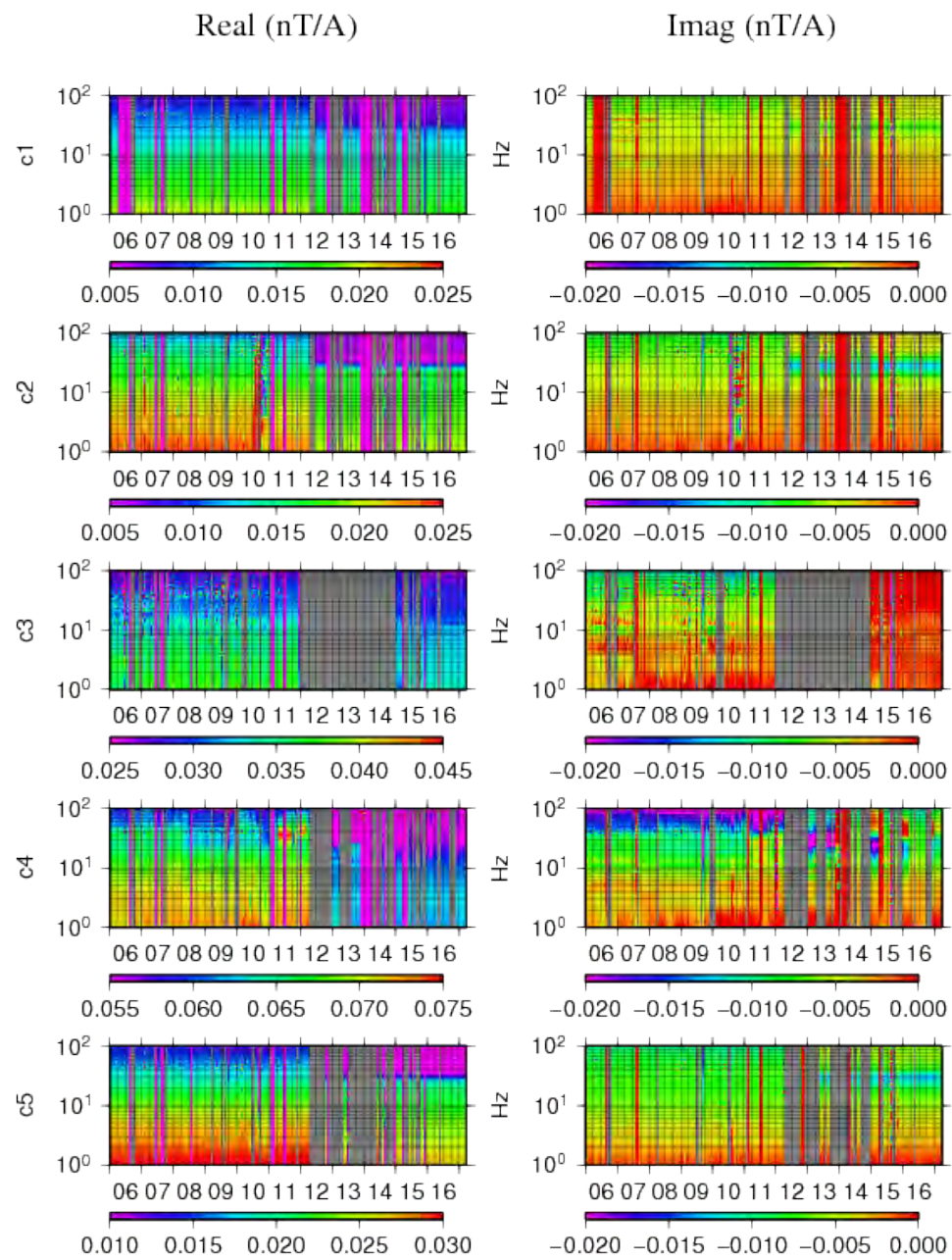
RAW data plot

2017/03/28



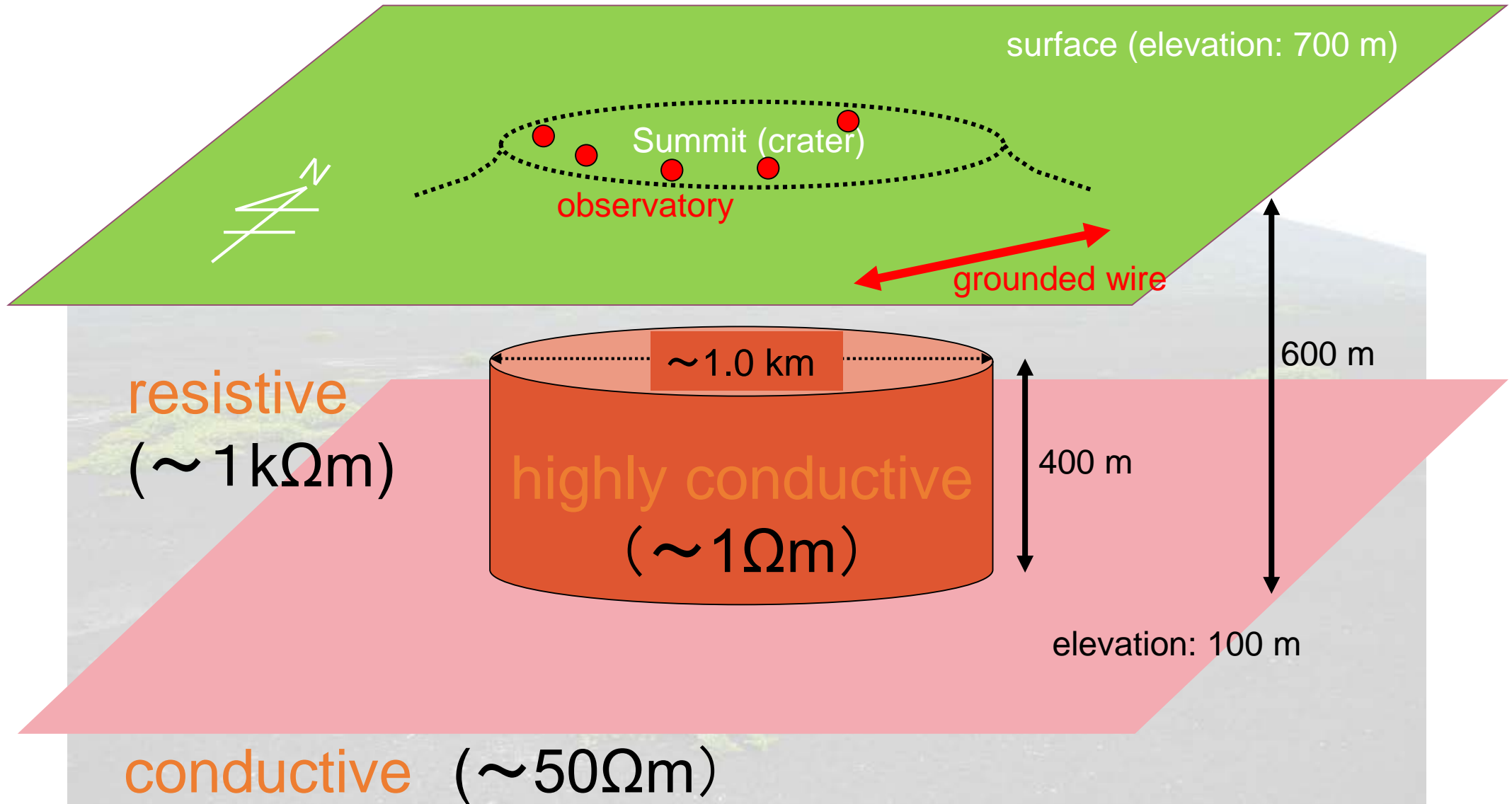
Response plot

2006-01-01 ~ 2017-03-28



Structure beneath Mt. Mihara (Utada 2003, Takahashi 2006)

→ Two layer with a highly conductive column



I try to determine 3 model parameters by grid search inversion.
(Other parameters are fixed.)

- **Radius of column** (0, 100, 200, 300, 400, 500 m)
- **Resistivity of column** (1, 2, 5, 10, 20, 50, 100 Ωm)
- **Resistivity of top layer** (0.1, 0.2, 0.5, 1.0, 2.0, 5.0, 10.0 $\text{k}\Omega\text{m}$)

9 Frequencies : 1, 3, 5, 7, 9, 17, 33, 65, and 99 Hz

Best solution

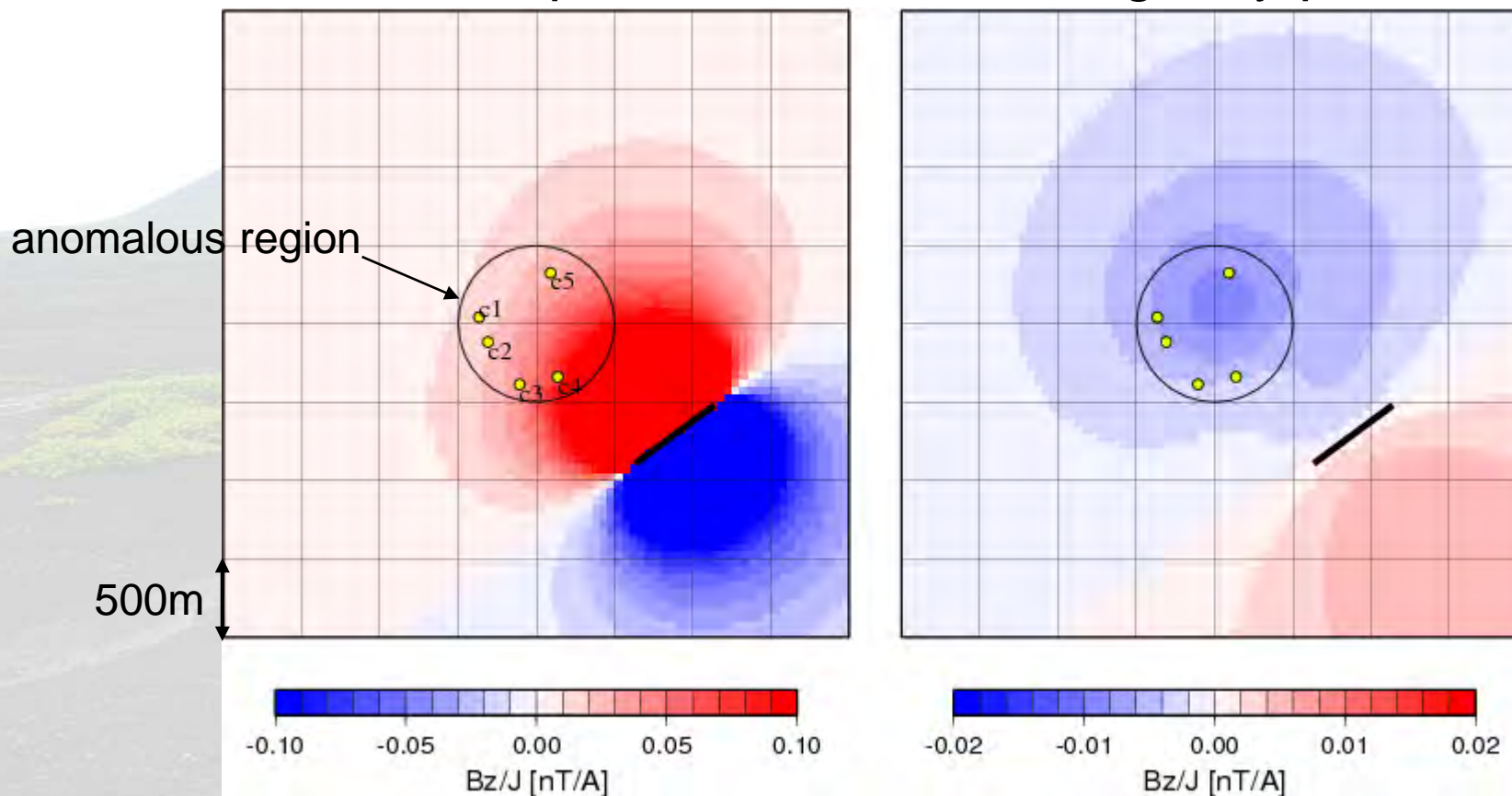
- **Radius of column** : 200 m
- **Resistivity of column** : 1 Ωm
- **Resistivity of top layer** : 0.2 $\text{k}\Omega\text{m}$

Numerical example : Forward modeling

B_z / J [nT/A] at 33 Hz

Real part

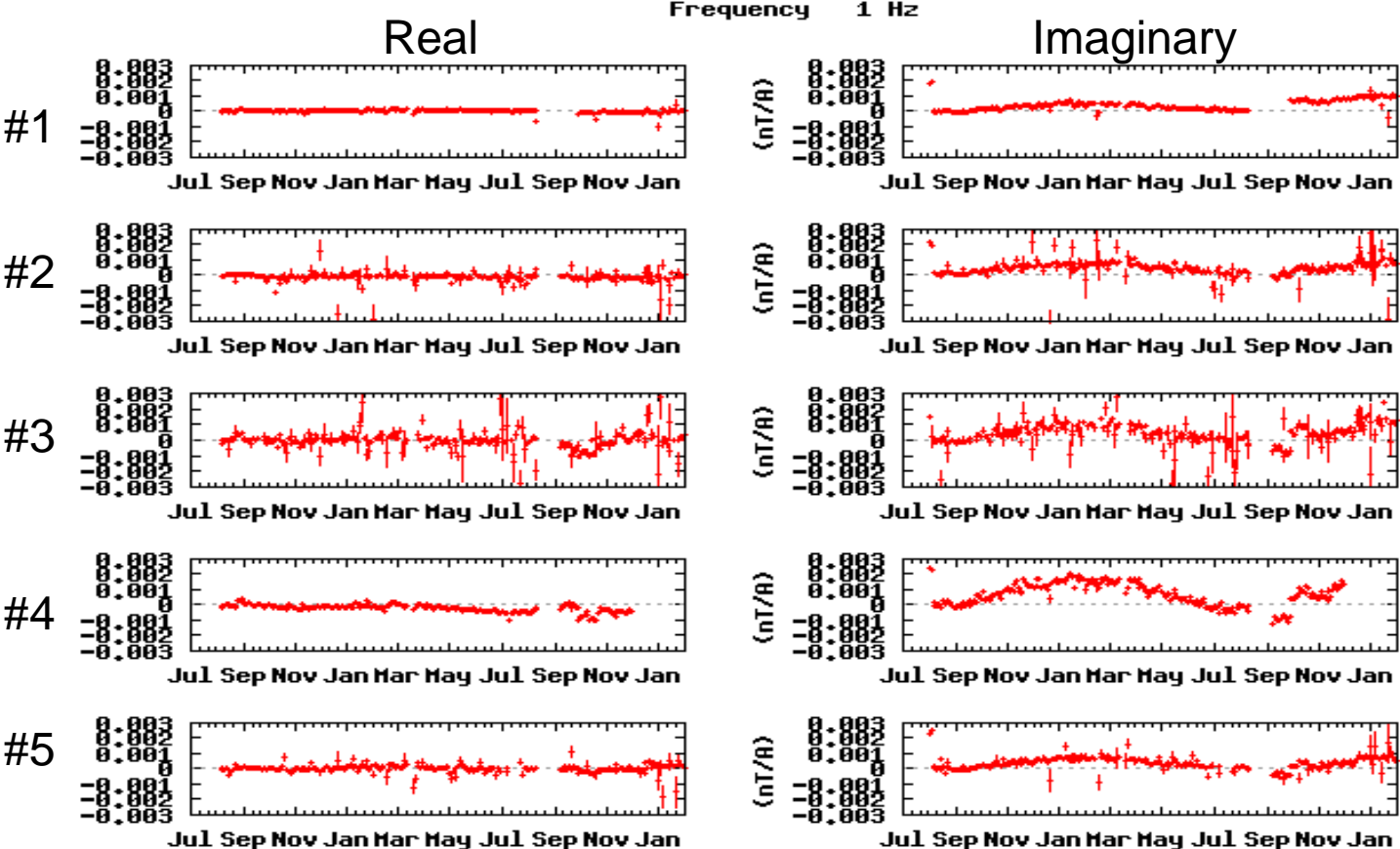
Imaginary part



Grid size : 50 m x 50 m x 25 m

Running spectrum of ACTIVE response at the frequency of 1 Hz

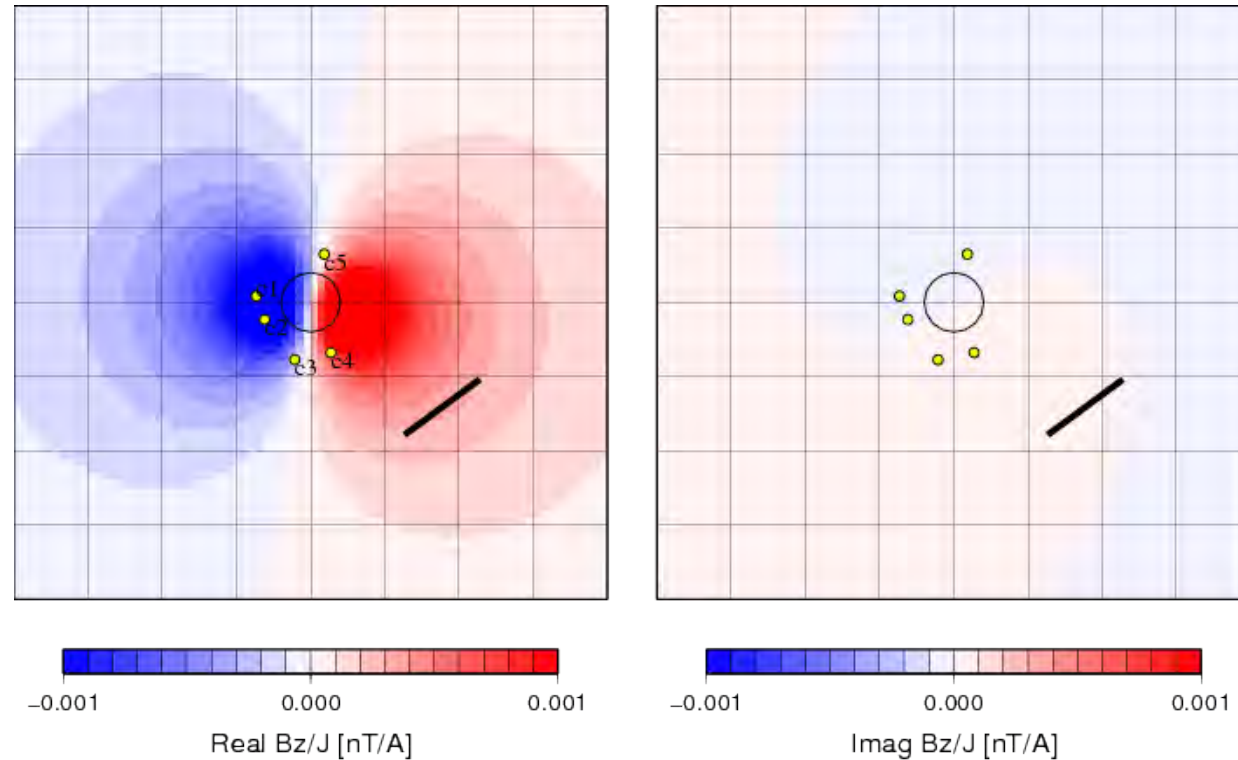
→ Annual variation is visible



→ Real part has much less variation than imaginary part.
Changes of imaginary part has the same phase at all the sites

Numerical test 1

In the case that some conductor rises up beneath the “A” crater



Real part is much bigger than imaginary part.

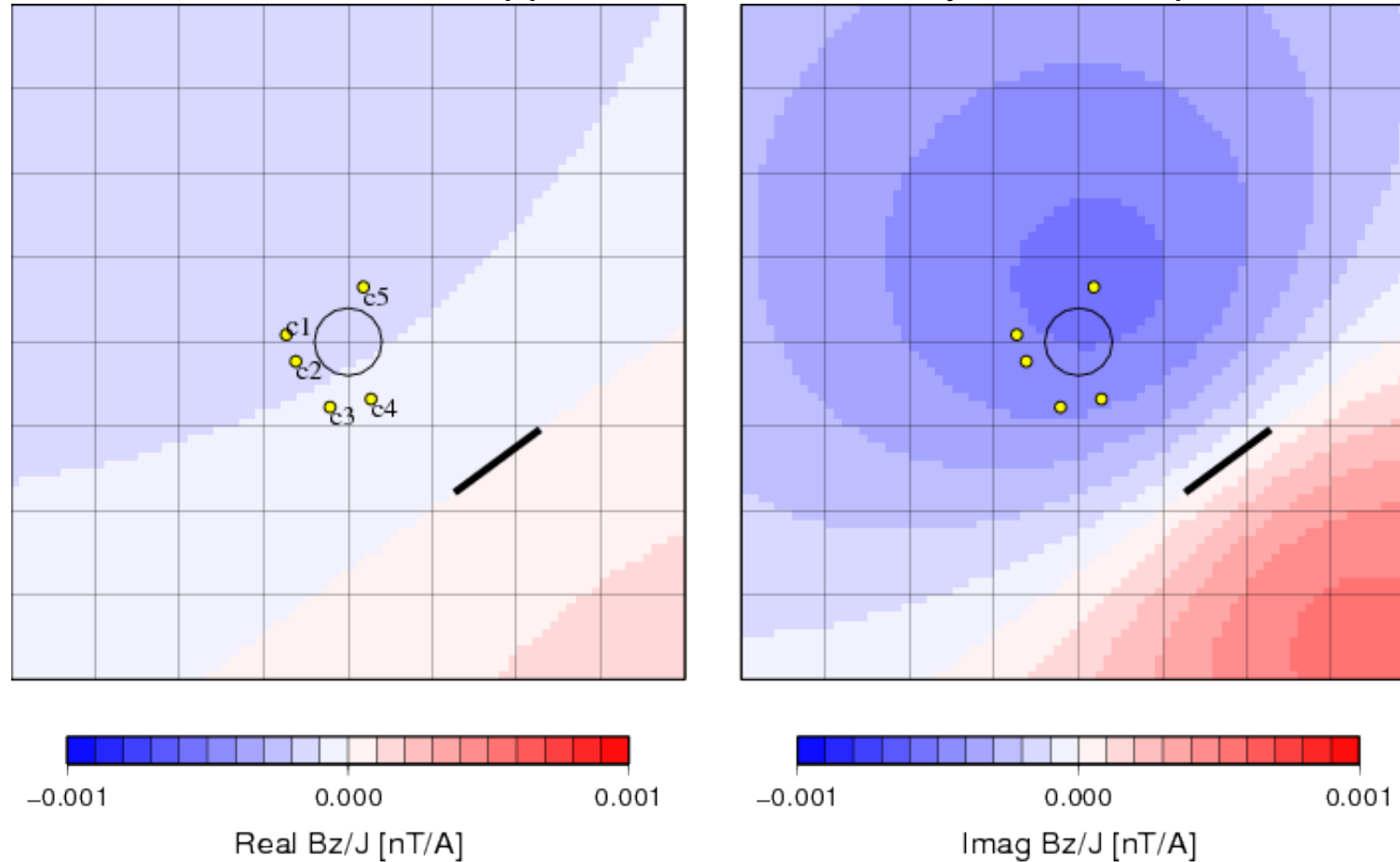
Phase are not the same at all the sites.



Observed annual change seems not to be caused by volcanic activity

Numerical test 2

In the case that the upper bound of lower layers rises up



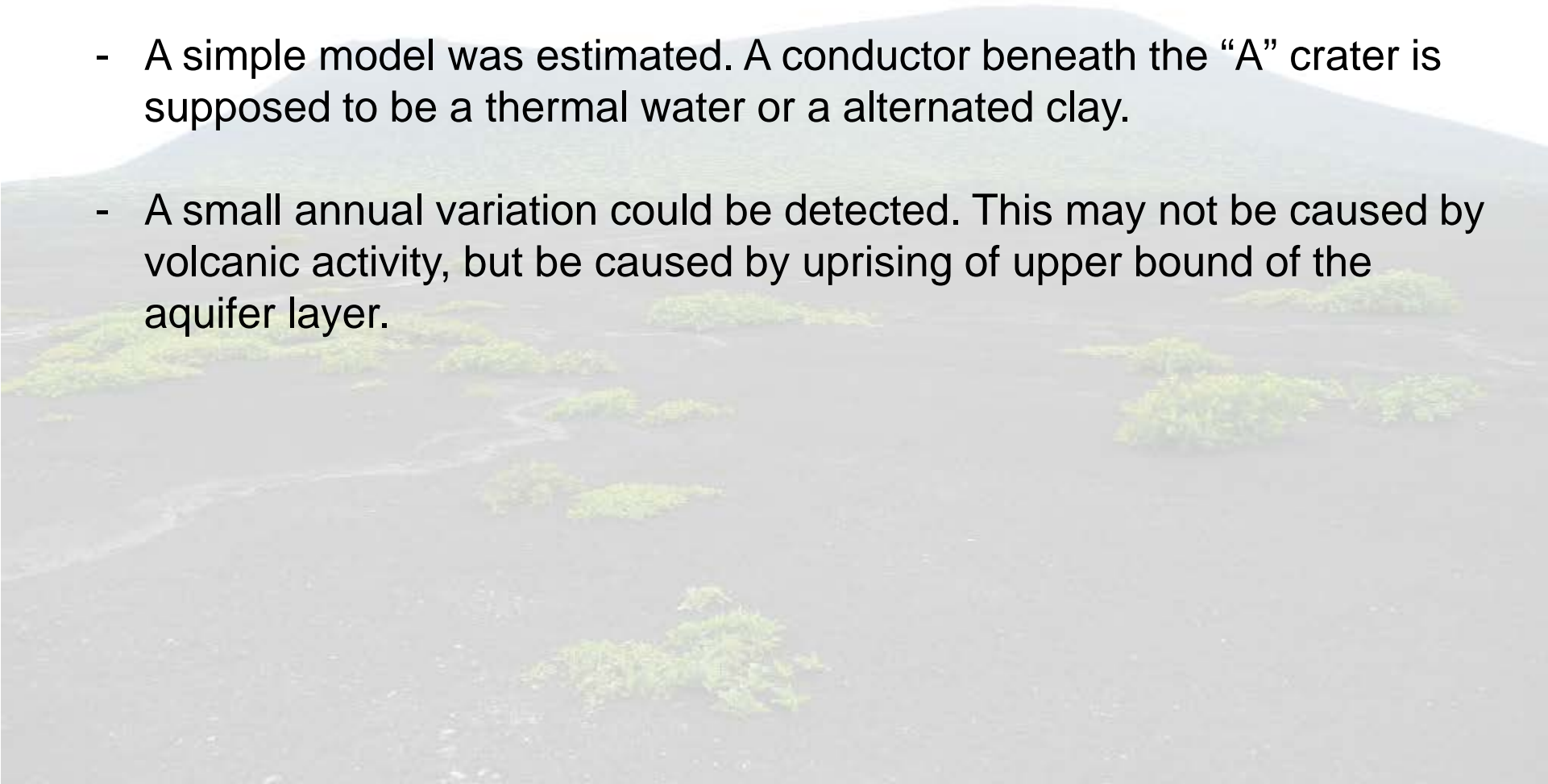
Imaginary part is much bigger than real part

Phases are almost the same at all the sites

→ It may be caused by the change of depth of the surface of aquifer layer

Summary


- We're conducting continuous measurement by CSEM method
- A fast 3-D numerical forward calculation code was developed
- A simple model was estimated. A conductor beneath the "A" crater is supposed to be a thermal water or a alternated clay.
- A small annual variation could be detected. This may not be caused by volcanic activity, but be caused by uprising of upper bound of the aquifer layer.



Repeated aeromagnetic survey by using unmanned helicopter

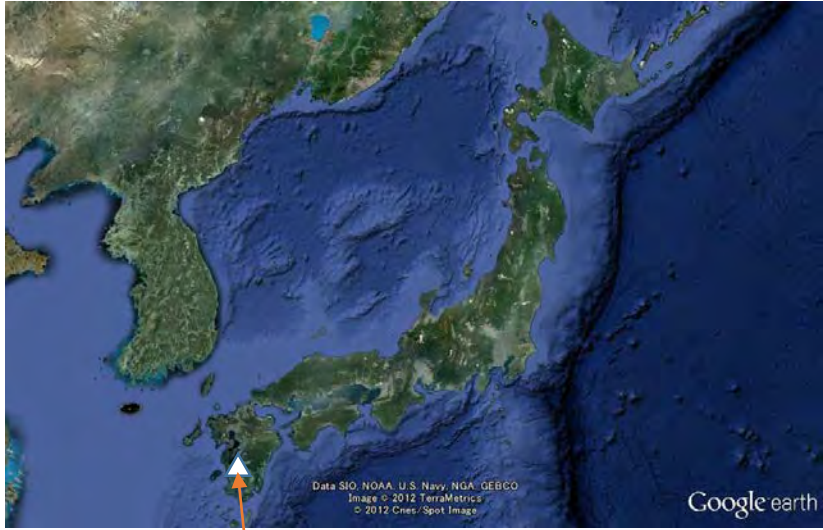
An unmanned helicopter is shown in flight against a blue sky with white clouds. A thin cable hangs from the helicopter, suggesting it is carrying a sensor or instrument for an aeromagnetic survey.

Outline

- Introduction of Shinmoe-dake volcano and its activity
 - Aeromagnetic surveys by unmanned helicopter
 - Detection of temporal change of geomagnetic field intensity
 - Summary
- 
- The bottom of the slide shows a dark silhouette of a volcano, likely Shinmoe-dake, against the sky. The volcano has a distinct peak and a smaller secondary peak to its right.

Shinmoe-dake volcano

Latest event : 2011 eruption



Shinmoe-dake volcano



2011 eruptions



After eruptions

Photo by T. Kaneko (ERI, Univ. Tokyo)

Shinmoedake 2011 eruption events and aeromagnetic surveys

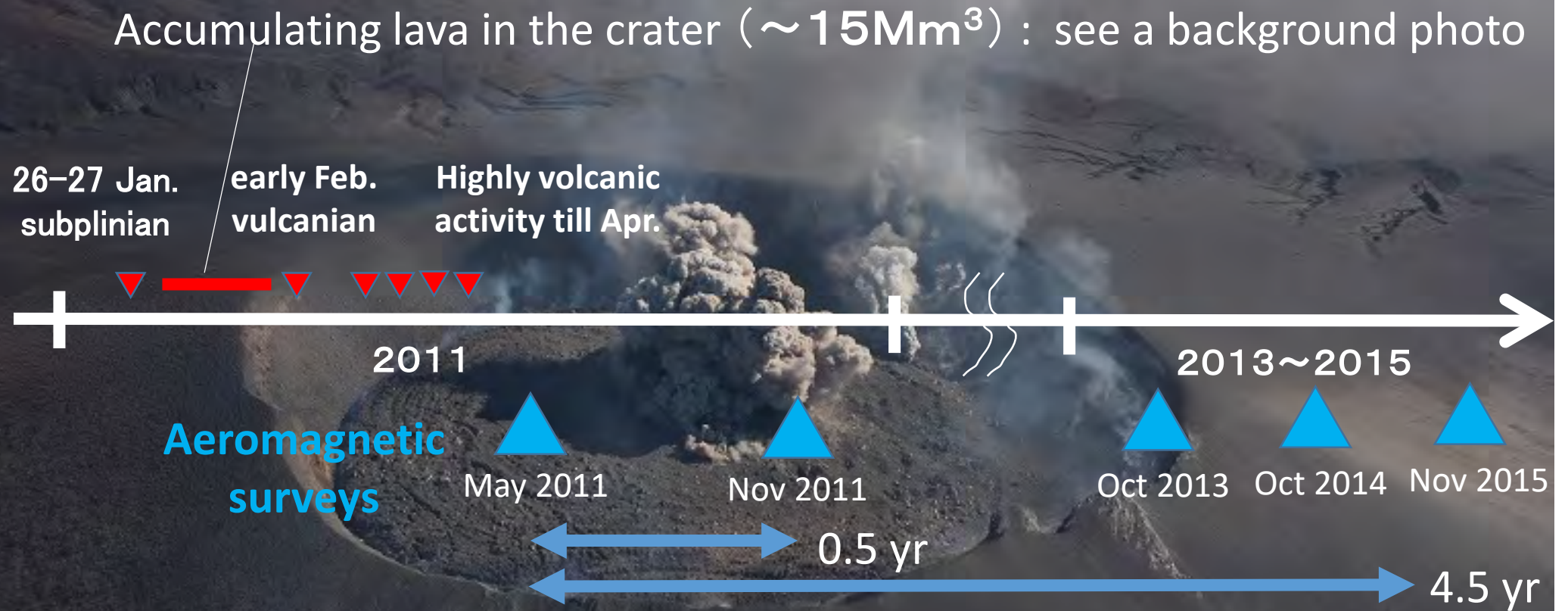


Photo by T. Kaneko (ERI, Univ. Tokyo)

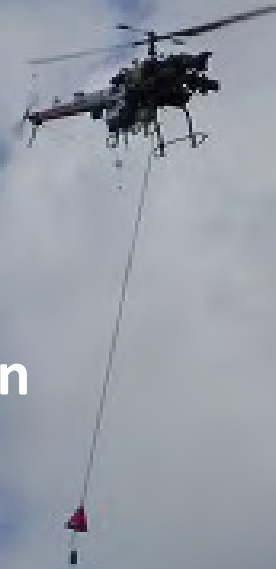
Purpose

- To elucidate the distribution of magnetization at the region close to Shinmoe-dake volcano
- To detect the temporal change of magnetization

Advantage to use unmanned helicopter

Unmanned helicopter

- Can take a flight above active volcanos safely.
- Can fly so low that highly-resolved magnetization can be measured.
- Can fly so precisely that it can fly on the same course again.



Aeromagnetic surveys by unmanned helicopter



YAMAHA RMAX-G1

Magnetometer



Base station

Unmanned helicopter - commonly used for spraying agricultural chemicals

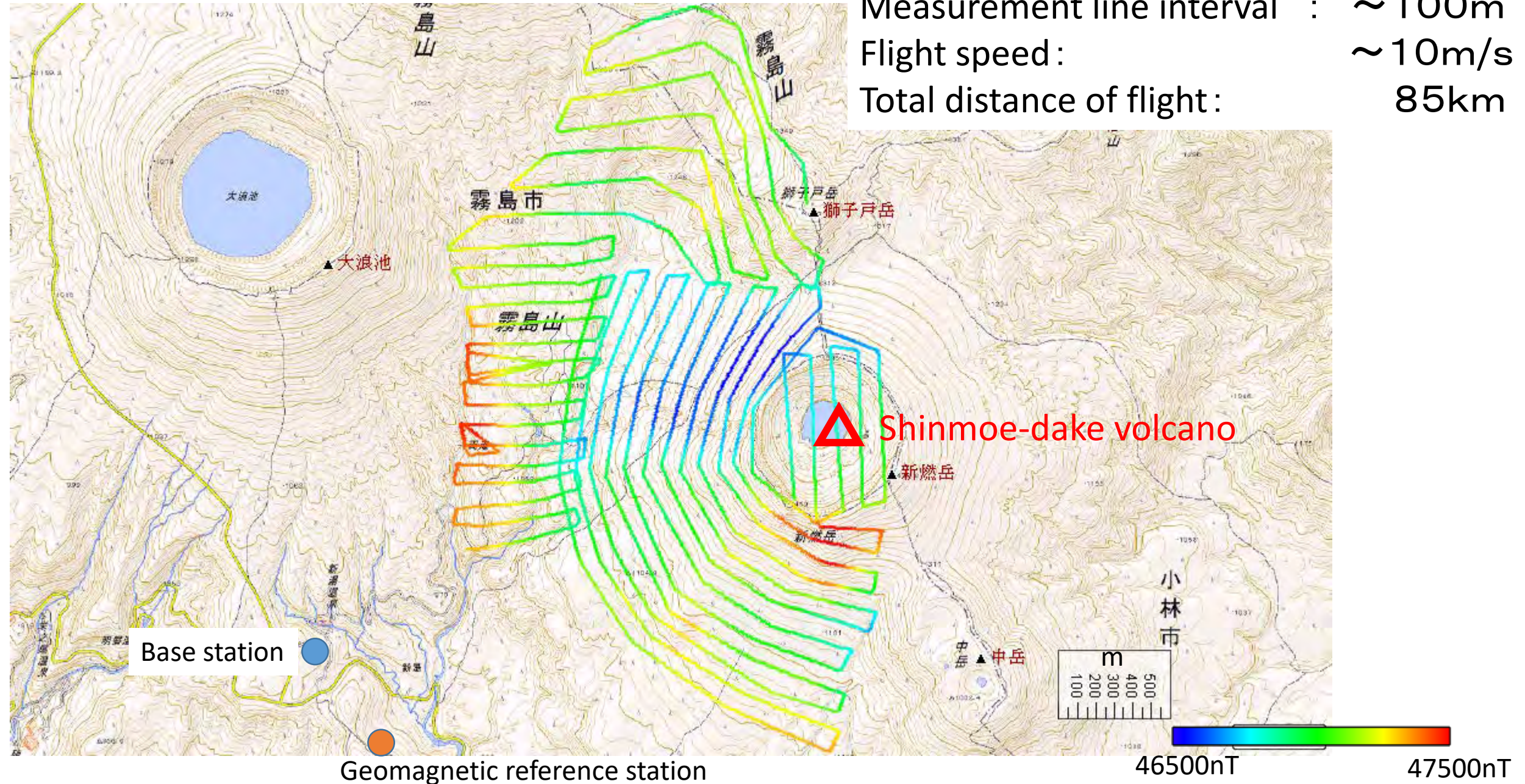
Magnetometer – Cesium optical pumping total intensity magnetometer

The helicopter is rent from YAMAHA and is operated by YAMAHA staffs

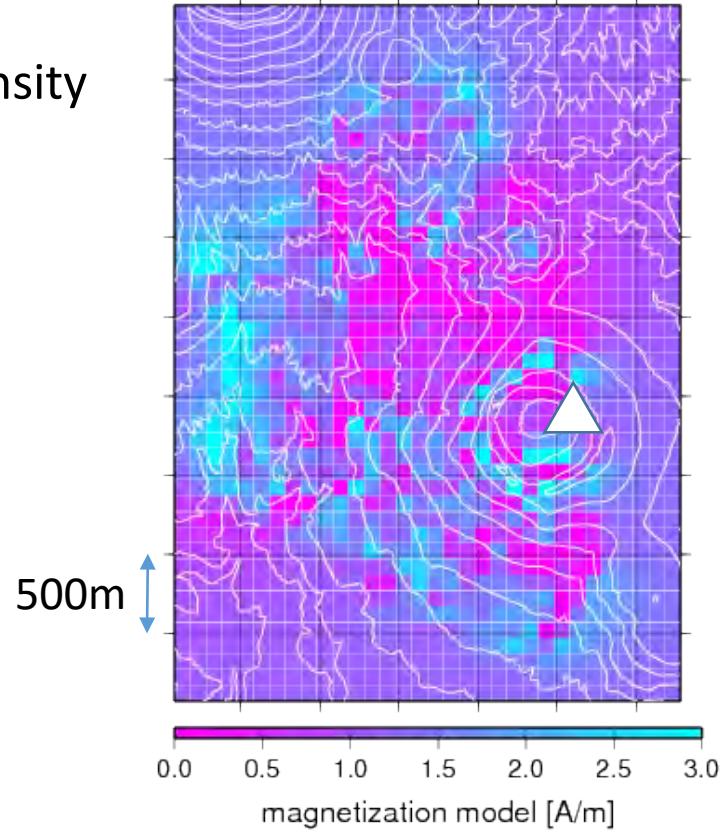


Survey map (4th survey 22nd Oct 2014)

Flight altitude above ground : $\sim 100\text{m}$
Measurement line interval : $\sim 100\text{m}$
Flight speed : $\sim 10\text{m/s}$
Total distance of flight : 85km



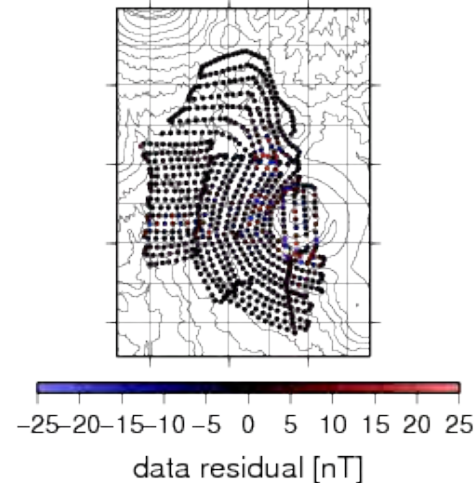
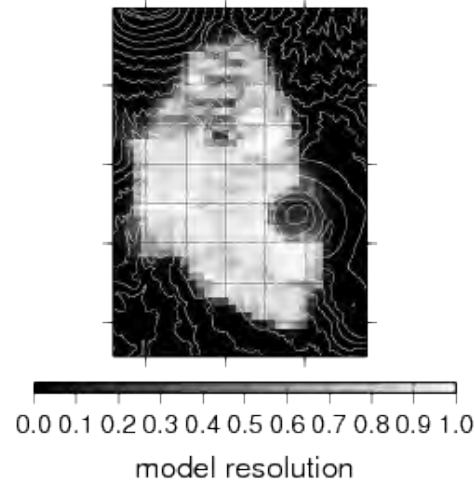
2-D estimated magnetization intensity



Mean value of magnetization

~ 1.2 A/m

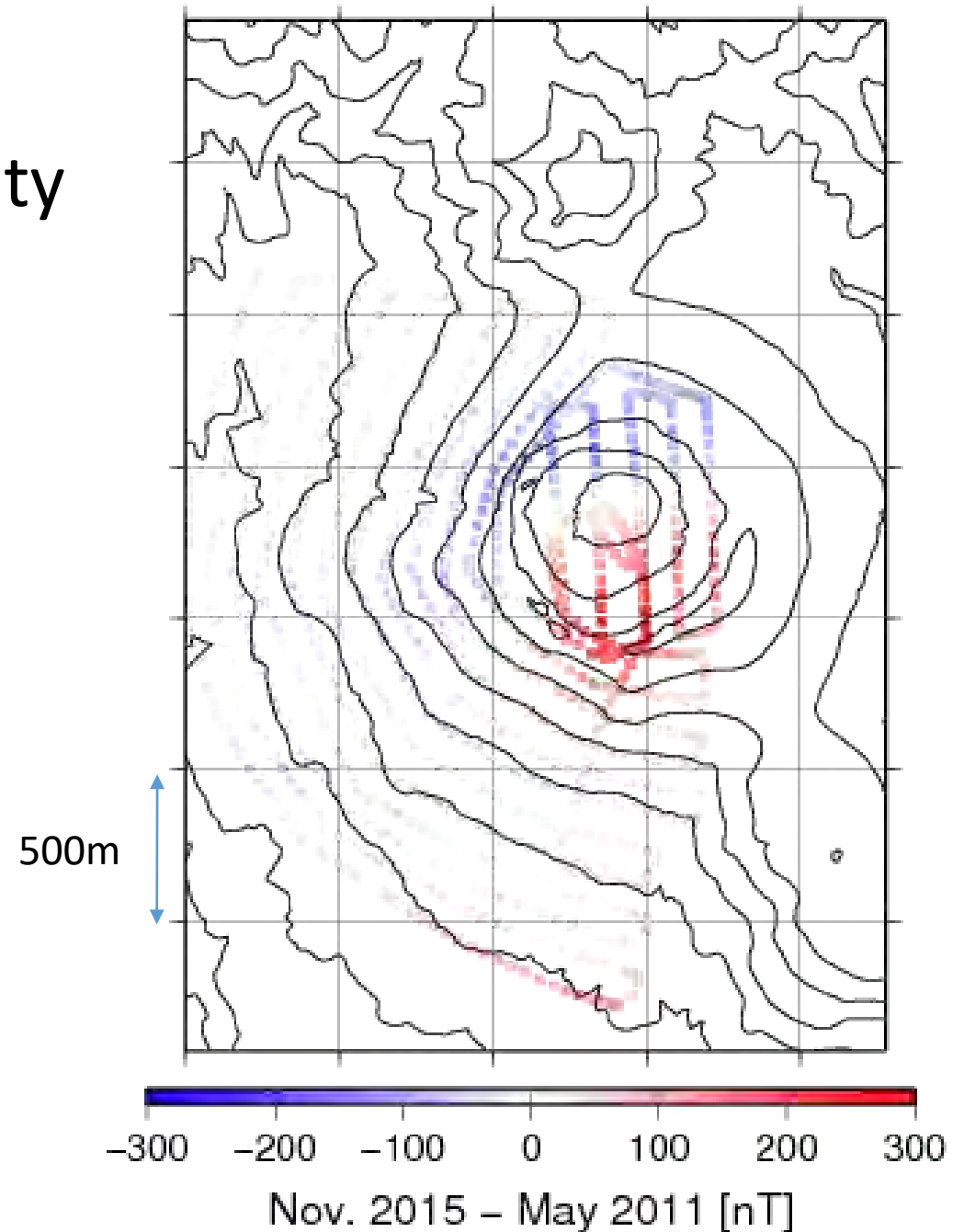
✖ rock magnetization
1.1 ~ 8.9A/m
(Utada et al., 2000)



Temporal change of Geomagnetic total intensity

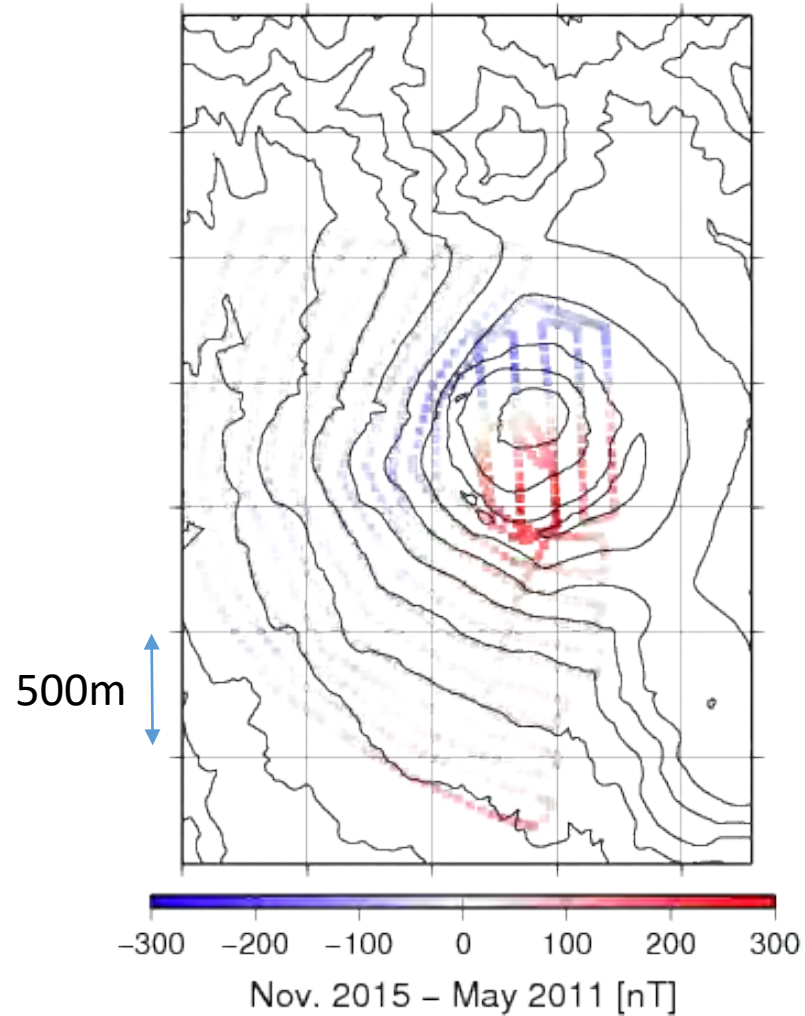
5th survey – 1st survey

Nov 2015 - May 2011
(4.5 years)

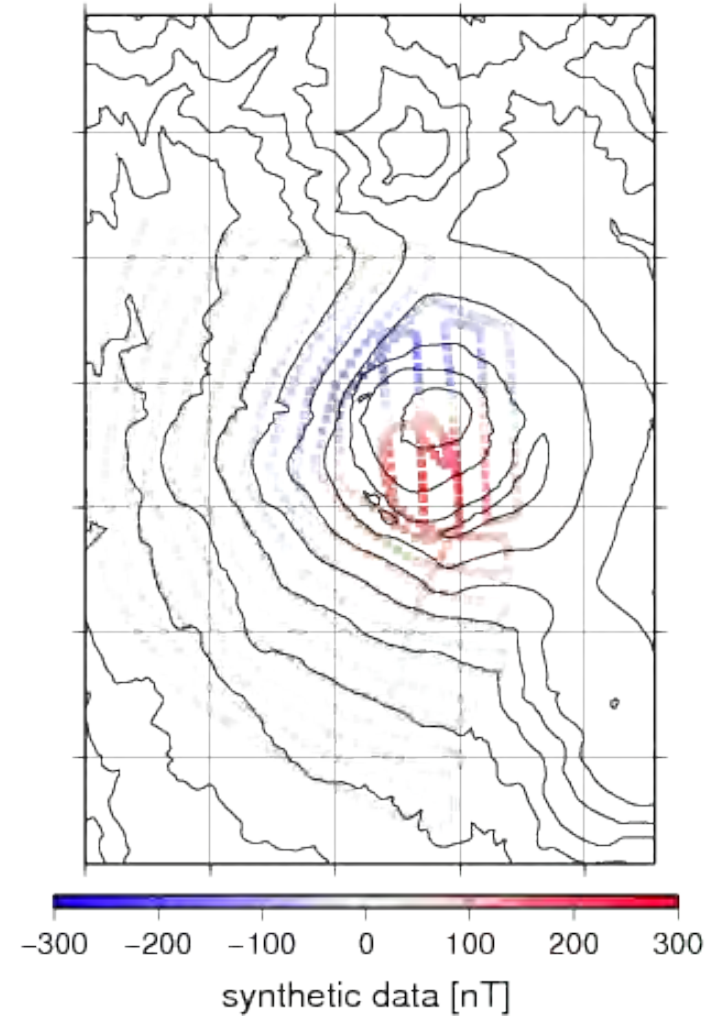


Estimate of dipole moment beneath crater

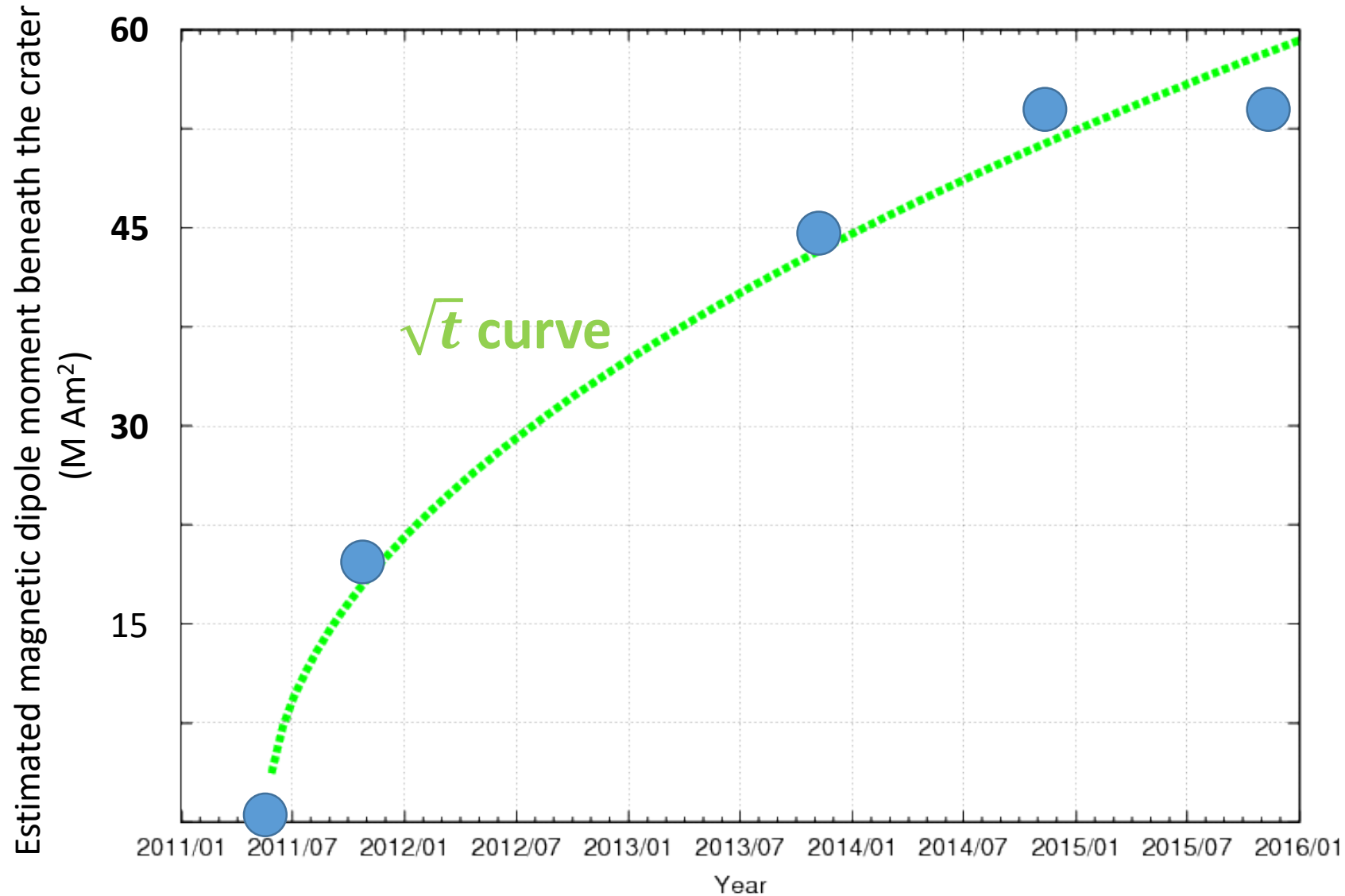
Temporal change of experimental data
Nov. 2015 – May 2011



Synthetic total intensity change
supposing 54 M Am^2 beneath the crater

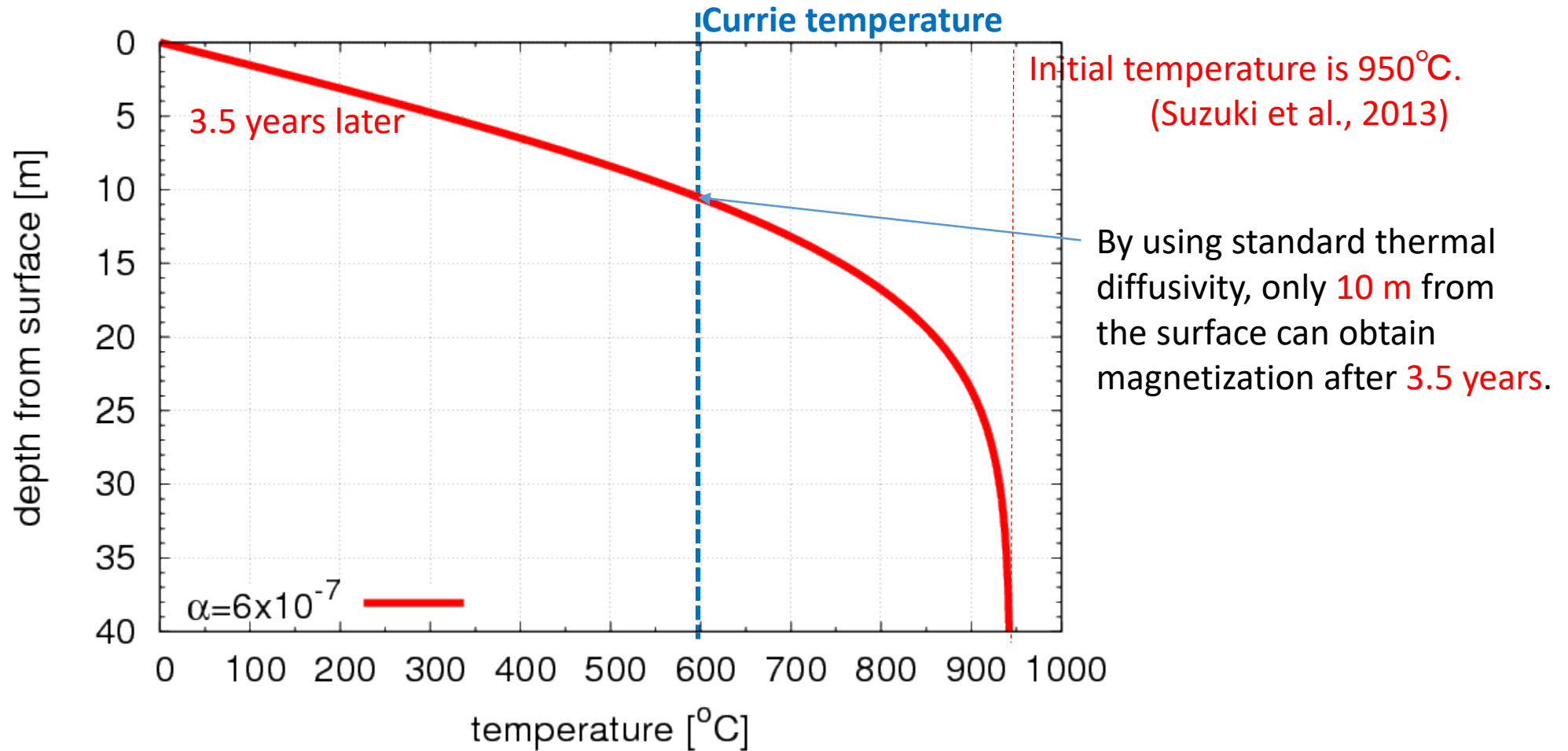


Temporal change of estimated dipole moment beneath the crater



It indicates the lava is cooling by thermal diffusion from the surface.

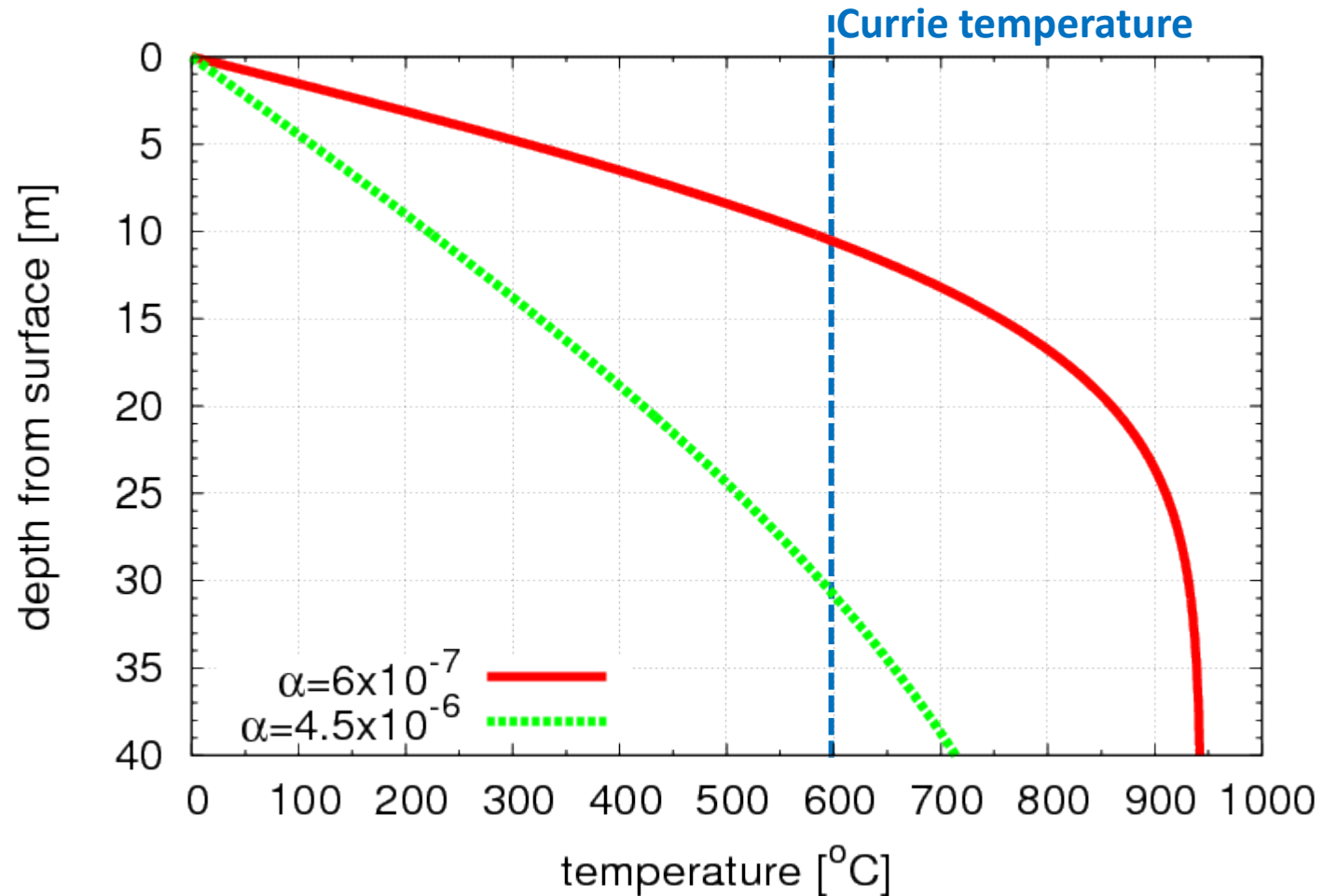
Depth-temperature distribution in 1-D thermal diffusion



→ To explain the dipole moment, the magnetization of lava is about 32 A/m **TOO LARGE!**

Supposing magnetization of lava by 10 A/m (Utada et al. 2000)

➔ To explain dipole moment, 30 m from the surface must be magnetized.



➔ “effective” thermal diffusivity $4.5 \times 10^{-6} \text{ m}^2/\text{s}$

“Effective” thermal diffusivity :

Water penetrating in crater may be important role to raise the diffusivity

Heat Balance

Heat diffused by “effective” thermal diffusivity

2.15×10^{16} J @ 2014 Oct.

5.67×10^{15} J @ 2011 Nov.

Radius of lava cake : 250m

Density of lava : 2500 kg/m^3

Initial lava temperature : 950°C

Latent heat of lava : $2.1 \times 10^5 \text{ J/kg}$

Specific heat capacity of lava : 10^3 J/kg/K



Heat to vapor water of lake and rainfalls in crater

1.61×10^{16} J @ 2014 Oct.

4.68×10^{15} J @ 2011 Nov.

Radius of crater (rainfall area) : 375m

Density of water : 1000 kg/m^3

Initial and vaporizing temperature : 0 and 100°C

Latent heat of water : $2.3 \times 10^6 \text{ J/kg}$

Specific heat capacity of water : $4.2 \times 10^3 \text{ J/kg/K}$

rain amount data is taken from Ebino observatory of JMA

Summary

5 repeated survey have been carried out by using unmanned helicopter

Notable temporal change by 400 nT maximum were clearly detected above the crater.

This change may be supposed to be due to cooling the lava accumulating in the crater at 2011 eruption events.

Magnetic intensity is increasing by square root of elapsed time.

It indicates that cooling lava is done by thermal diffusion from the surface.

Diffusion rate is so fast and water vaporeing may play an important role to raise it.

